

Use an L5 × 3½ × ¾

(b) $P_u = D + L = 28 + 84 = 112$ kips

$$\text{Required } A_g = \frac{P_u}{F_t} = \frac{P_u}{0.6F_y} = \frac{112}{0.6(36)} = 5.19 \text{ in.}^2$$

$$\text{Required } A_e = \frac{P_u}{0.5F_u} = \frac{112}{0.5(58)} = 3.86 \text{ in.}^2$$

$$\text{Required } r_{\min} = \frac{L_c}{300} = \frac{18(12)}{300} = 0.72 \text{ in.}$$

Try L5 × 3½ × ¾

$$A_g = 5.85 \text{ in.}^2 > 5.19 \text{ in.}^2 \quad (\text{OK})$$

$$r_{\min} = r_z = 0.744 \text{ in.} > 0.72 \text{ in.} \quad (\text{OK})$$

$$A_n = 5.85 - 0.75(1 + 3/16) = 4.959 \text{ in.}^2$$

$$A_e = A_n U = 4.959(0.80) = 3.97 \text{ in.}^2 > 3.86 \text{ in.}^2 \quad (\text{OK})$$

Use an L5 × 3½ × ¾

3.6-2

(a) $P_u = 1.2D + 1.6L = 1.2(100) + 1.6(50) = 200.0$ kips

$$\text{Required } A_g = \frac{P_u}{0.9F_y} = \frac{200}{0.9(36)} = 6.17 \text{ in.}^2$$

$$\text{Required } A_e = \frac{P_u}{0.75F_u} = \frac{200}{0.75(58)} = 4.60 \text{ in.}^2$$

$$\text{Required } r_{\min} = \frac{L_c}{300} = \frac{20 \times 12}{300} = 0.8 \text{ in.}$$

Try C12 × 25

$$A_g = 7.34 \text{ in.}^2 > 6.17 \text{ in.}^2 \quad (\text{OK})$$

$$r_{\min} = r_y = 0.779 \text{ in.} < 0.8 \text{ in.} \quad (\text{N.G.})$$

(Although this value for the radius of gyration does not quite satisfy the AISC recommendation for maximum slenderness, tensile strength is not affected by slenderness, so some leeway is permitted. Therefore, we will consider this value acceptable.)

$$A_n = 7.34 - 0.387(1 + 3/16)(2) = 6.421 \text{ in.}^2$$

$$U = 1 - \frac{\bar{x}}{\bar{e}} = 1 - \frac{0.674}{6} = 0.8877$$

Discrete Events Simulation 6th Edition Solution Manual

A. Alan B. Pritsker



Discrete Events Simulation 6th Edition Solution Manual:

Emerging Solutions for Future Manufacturing Systems Luis M. Camarinha-Matos, 2006-01-04 Industries and particularly the manufacturing sector have been facing difficult challenges in a context of socio economic turbulence characterized by complexity as well as the speed of change in causal interconnections in the socio economic environment In order to respond to these challenges companies are forced to seek new technological and organizational solutions In this context two main characteristics emerge as key properties of a modern automation system agility and distribution Agility because systems need not only to be flexible in order to adjust to a number of a priori defined scenarios but rather must cope with unpredictability Distribution in the sense that automation and business processes are becoming distributed and supported by collaborative networks Emerging Solutions for Future Manufacturing Systems includes the papers selected for the BASYS 04 conference which was held in Vienna Austria in September 2004 and sponsored by the International Federation for Information Processing IFIP

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